

Sparse Autoencoder Notation Summary

From Ufldl

Here is a summary of the symbols used in our derivation of the sparse autoencoder:

| Symbol | Meaning |
|----------------------|---|
| x | Input features for a training example, $x \in \mathbb{R}^n$. |
| y | Output/target values. Here, y can be vector valued. In the case of an autoencoder, $y = x$. |
| $(x^{(i)}, y^{(i)})$ | The i -th training example |
| $h_{W,b}(x)$ | Output of our hypothesis on input x , using parameters W, b . This should be a vector of the same dimension as the target value y . |
| $W_{ij}^{(l)}$ | The parameter associated with the connection between unit j in layer l , and unit i in layer $l + 1$. |
| $b_i^{(l)}$ | The bias term associated with unit i in layer $l + 1$. Can also be thought of as the parameter associated with the connection between the bias unit in layer l and unit i in layer $l + 1$. |
| θ | Our parameter vector. It is useful to think of this as the result of taking the parameters W, b and "unrolling them into a long column vector". |
| $a_i^{(l)}$ | Activation (output) of unit i in layer l of the network. In addition, since layer L_1 is the input layer, we also have $a_i^{(1)} = x_i$. |
| $f(\cdot)$ | The activation function. Throughout these notes, we used $f(z) = \tanh(z)$. |
| $z_i^{(l)}$ | Total weighted sum of inputs to unit i in layer l . Thus, $a_i^{(l)} = f(z_i^{(l)})$. |
| α | Learning rate parameter |
| s_l | Number of units in layer l (not counting the bias unit). |
| n_l | Number layers in the network. Layer L_1 is usually the input layer, and layer L_{n_l} the output layer. |
| λ | Weight decay parameter. |
| \hat{x} | For an autoencoder, its output; i.e., its reconstruction of the input x . Same meaning as $h_{W,b}(x)$. |
| ρ | Sparsity parameter, which specifies our desired level of sparsity |
| $\hat{\rho}_i$ | The average activation of hidden unit i (in the sparse autoencoder). |
| β | Weight of the sparsity penalty term (in the sparse autoencoder objective). |

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